

An Equational Axiomatization of Dynamic Threads: Towards Concurrency as an Algebraic Effect

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Introduction

Denotational semantics is about finding models of programs in order to:

- ▶ **reason** about program behaviour,
- ▶ and to compare them more easily.
- ▶ Models should be **modular**, can combine different features.

Methods:

- ▶ the simply-typed λ -calculus as a core programming language;
- ▶ category theory as a tool for organizing models.

Introduction

These methods work well for functional programming: a program is a function that takes an input and returns a value.

But programs interact with the environment e.g.:

- ▶ manipulating memory,
 - ▶ taking input from a keyboard,
 - ▶ probabilistic computation.
- } **Computational effects**
[Moggi], [Plotkin&Power]

Programs interact with other programs running **concurrently**.

In this talk:

Concurrency can be treated as a computational effect.

To obtain equational reasoning in a programming language setting.

Related work: ACP, concurrent Kleene algebra, [van Glabbeek&Plotkin], [Abadi&Plotkin]

Outline

- 1 Background on effects
- 2 Concurrency in this talk
- 3 Operational semantics for dynamic threads
- 4 An algebraic theory of dynamic threads
- 5 The pomset model of dynamic threads
- 6 Prospects

Moggi's setting for denotational semantics of effects [LICS'89]

- ▶ A cartesian category \mathcal{C} (binary products, terminal object),
- ▶ a strong monad T on \mathcal{C} , and
- ▶ Kleisli exponentials (objects $B \Rightarrow TC$).

Enough to model simply-typed lambda-calculus (STLC) with effects.

Types and contexts are interpreted as objects $\llbracket A \rrbracket, \llbracket \Gamma \rrbracket$ of \mathcal{C} .

Effectful terms are interpreted as morphisms:

$$\llbracket \Gamma \vdash^{\text{eff}} M : A \rrbracket : \llbracket \Gamma \rrbracket \rightarrow T\llbracket A \rrbracket$$

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Enough to model simply-typed lambda-calculus (STLC) with effects.

Example of a strong monad (on **Set**):

$$TX = 2 \Rightarrow (X \times 2)$$

which models reading and writing one bit of memory, and returning a value of type X .

Plotkin's and Power's framework of algebraic effects

Idea: effects are realised by operations and equations that **generate** a monad, but are not identified with the monad.

They work with presentations of algebraic theories, in the sense of universal algebra.

Theorem [Lawvere, Linton]

To give a finitary monad on the category of sets is equivalent to giving an algebraic theory.

(Here “algebraic theory” is a suitable presentation-independent notion.)

An algebraic theory determines a monad by the free-algebra construction.

Plotkin's and Power's framework of algebraic effects

Idea: effects are realised by operations and equations that **generate** a monad, but are not identified with the monad.

Example. The one-bit state monad $TX = 2 \Rightarrow (X \times 2)$ is generated by operations:

$$\frac{\Gamma \vdash^{\text{eff}} M_0 : A \quad \Gamma \vdash^{\text{eff}} M_1 : A}{\Gamma \vdash^{\text{eff}} \text{get}(M_0, M_1) : A}$$

$$\frac{\Gamma \vdash^{\text{eff}} M : A}{\Gamma \vdash^{\text{eff}} \text{put}_0(M) : A}$$

$$\frac{\Gamma \vdash^{\text{eff}} M : A}{\Gamma \vdash^{\text{eff}} \text{put}_1(M) : A}$$

and equations, where $i, i' \in \{0, 1\}$

$$\text{put}_i(\text{get}(x_0, x_1)) = \text{put}_i(x_i)$$

$$\text{put}_i(\text{put}_{i'}(x)) = \text{put}_{i'}(x)$$

$$\text{get}(\text{put}_0(x), \text{put}_1(x)) = x$$

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What I mean by concurrency in this talk

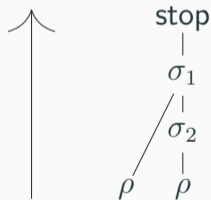
Dynamic threads

Programs create new threads dynamically, and wait for them to finish.
E.g. POSIX-like `fork`.

Concurrent programs denote **partial orders with labels** (pomsets).

Example:

let $y = \text{fork}()$ in case $(\text{act}_\rho(); y)$
of $\{ \text{inj}_1(a) \Rightarrow \text{wait}(a); \text{act}_{\sigma_1}(); \text{stop}()$
 $\text{inj}_2() \Rightarrow \text{act}_{\sigma_2}(); \text{stop}() \}$

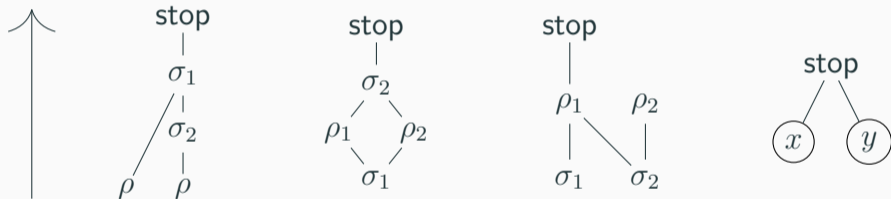


- ▶ **Labels** denote observable actions.
- ▶ **Partial order** denotes observable dependencies.

What I mean by concurrency in this talk

Concurrent programs denote **partial orders with labels** (pomsets).

More examples of pomsets that are denotations:



Pomsets are a long-established model of true concurrency.

e.g. [Nielsen et al'81], [Pratt'86]. (In this work, pomsets without the conflict of event structures.)

Related work — Gap between theory and practice

Algebraic effects inspired **concurrency libraries** via effect handlers
e.g. in OCaml [Sivaramakrishnan et al'21], in WebAssembly [Phipps-Costin et al'23]
Not clear how these tie to theoretical foundations of effects.

Concurrency theory:

- ▶ process algebra;
- ▶ pomsets, event structures e.g. [Nielsen et al'81], [Pratt'86];
- ▶ concurrent Kleene algebra [Hoare et al'11];

Not clear how these apply to the semantics of functional programming
(i.e. extensions of simply-typed lambda calculus).

Related work — Algebraic effects for concurrency

- (1) Free-algebra models of the π -calculus [Stark'08]
- (2) CSP using algebraic effects and handlers [van Glabbeek&Plotkin'10]
- (3) Algebraic theories for shared state concurrency [Dvir et al'22, '25]
- (4) Cooperative threads with shared state [Abadi&Plotkin'10]

These are all **interleaving models**.

In (1)-(3), parallel composition is not an algebraic effect.

In this talk: **true concurrency** semantics for a core functional programming language. **fork** is an algebraic effect.

Summary of this work

Idea: treat forking threads and waiting for them as operations in the framework of algebraic effects.

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- (3) **Main theorem:** characterize the free models of this algebraic theory using pomsets.
 \implies A monad for denotational semantics of STLC + [fork](#), [wait](#).

Summary of this work

Idea: treat forking threads and waiting for them as operations in the framework of algebraic effects.

- (1) A natural operational semantics.
- (2) An algebraic theory that matches the operational semantics.
- (3) **Main theorem:** characterize the free models of this algebraic theory using pomsets.
 \implies A monad for denotational semantics of STLC + [fork](#), [wait](#).
- (4) Prove the denotational semantics matches the operational semantics.
(With the help of the algebraic presentation of the monad.)

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Calculus

Call-by-value lambda calculus extended with:

fork : unit \rightarrow tid + unit

wait : tid \rightarrow unit

stop : unit \rightarrow empty

act _{σ} : unit \rightarrow unit

tid base type of IDs of **sets of** threads; only introduced by fork

fork() spawns new child thread, copying the parent's continuation; can check whether parent or child by looking at result of fork

wait(*a*) the current thread waits for all threads in *a* to finish

stop() end current thread, unblocks all threads waiting for it

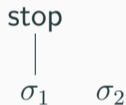
act _{σ} () performs observable action σ

Operational semantics by example

Operational semantics is a relation between pools of threads.

The observable behaviour of programs is captured by partial orders labelled by observable actions.

let $y = \text{fork}()$ in case y of $\{\text{inj}_1(a) \Rightarrow \text{act}_{\sigma_1}(); \text{stop}()$
 $\text{inj}_2() \Rightarrow \text{act}_{\sigma_2}(); \text{stop}()\}$



let $y = \text{fork}()$ in case y of $\{\text{inj}_1(a) \Rightarrow \text{wait}(a); \text{act}_{\sigma_1}(); \text{stop}()$
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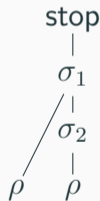


stop is extra structure, a maximal element.

Operational semantics by example

Operational semantics is a relation between pools of threads.

fork duplicates the continuation.

$$\{ [b] \text{let } y = \text{fork}() \text{ in case } (\text{act}_\rho(); y) \\ \text{of } \{ \text{inj}_1(a) \Rightarrow \text{wait}(a); \text{act}_{\sigma_1}(); \text{stop}() \\ \text{inj}_2() \Rightarrow \text{act}_{\sigma_2}(); \text{stop}() \} \}$$
$$\longrightarrow \{ [b] \text{case } (\text{act}_\rho(); \text{inj}_1(a)) \text{ of } \dots, \\ [a] \text{case } (\text{act}_\rho(); \text{inj}_2()) \text{ of } \dots \}$$


Operational semantics by example

stop discards the continuation.

let $y = \text{fork}()$ in case y

of { $\text{inj}_1(a) \Rightarrow \text{wait}(a); \text{act}_{\sigma_1}(); \text{stop}()$
 $\text{inj}_2() \Rightarrow \text{act}_{\sigma_2}(); \text{stop}(); \text{act}_{\rho}() \}$

stop
|
 σ_1
|
 σ_2

We will axiomatize fork, wait, stop, act _{σ} with 9 equations.

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Algebraic operations vs generic effects

- ▶ So far, **generic effects** e.g. `fork`, `wait`, natural for programming,
- ▶ correspond to **algebraic operations**, natural for algebra.

Given a **generic effect** $\underline{\text{op}} : A \rightarrow B$,

the **algebraic operation** `op` takes a value of type A and B continuations.

Example:

`fork` : `unit` \rightarrow `tid` + `unit`

VS

`fork`($a.x(a)$, y)

`fork` binds a new ID a , bound in $x(a)$.

a refers to the single thread y .

Algebraic operations vs generic effects

Given a **generic effect** $\underline{\text{op}} : A \rightarrow B$,
the **algebraic operation** op takes a value of type A and B continuations.

Example:

$\underline{\text{fork}} : \text{unit} \rightarrow \text{tid} + \text{unit}$ vs $\text{fork}(a.x(a), y)$

tid = type of IDs of sets of threads, has a semilattice structure.

- ▶ $a \oplus b : \text{tid}$ is the ID of the union of the sets of threads a and b
- ▶ $0 : \text{tid}$ is the empty set of threads.

Waiting on $a \oplus b$ means waiting on **all** threads in a and b to stop.

Algebraic operations vs generic effects

Given a **generic effect** $\underline{\text{op}} : A \rightarrow B$,
the **algebraic operation** op takes a value of type A and B continuations.

Example:

$\underline{\text{fork}} : \text{unit} \rightarrow \text{tid} + \text{unit}$ vs $\text{fork}(a.x(a), y)$

a is a **parameter** in a parameterized algebraic theory [Staton'13]. Extension of algebraic theories with binding. Has correspondence to monads.

Variables x, y, z take (a finite number of) parameters as input. Example:

$x : 1, y : 0 \mid \cdot \vdash \text{fork}(a.x(a), y)$ $z : 2 \mid a, b \vdash z(a, b)$

Algebraic operations vs generic effects

tid = type of IDs of sets of threads, has a semilattice structure.

fork($a.x(a), y$) fork : **unit** \rightarrow **tid** + **unit**

wait($u; x$) wait : **tid** \rightarrow **unit**

u is the ID of a set of threads; wait on all threads in u , continue as x

stop stop : **unit** \rightarrow **empty**

has no continuation

act _{σ} (x) act _{σ} : **unit** \rightarrow **unit**

performs action σ and continues as x

Could rewrite the example programs using algebraic operations.

An algebraic theory of dynamic threads

Interaction of `wait` with the semilattice structure of thread IDs.

$$\text{wait}(0; x) = x \quad (1)$$

$$\text{wait}(a; \text{wait}(b; x)) = \text{wait}(a \oplus b; x) \quad (2)$$

$$\text{wait}(a; x(b)) = \text{wait}(a; x(a \oplus b)) \quad (3)$$

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$$\text{wait}(a; x(b)) = \text{wait}(a; x(a \oplus b)) \quad (3)$$

The term `wait(a; stop)` acts as a unit for `fork`.

$$\text{fork}(a.\text{wait}(a; \text{stop}), x) = x \quad (4)$$

$$\text{fork}(b.x(b), \text{wait}(a; \text{stop})) = x(a) \quad (5)$$

An algebraic theory of dynamic threads

Interaction of **wait** with the semilattice structure of thread IDs.

$$\text{wait}(0; x) = x \quad (1)$$

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Operations **wait** and **fork** commute; **fork** is commutative and associative.

$$\text{wait}(b; \text{fork}(a.x(a), y)) = \text{fork}(a.\text{wait}(b; x(a)), \text{wait}(b; y)) \quad (6)$$

$$\text{fork}(a.\text{fork}(b.x(a, b), y), z) = \text{fork}(b.\text{fork}(a.x(a, b), z), y) \quad (7)$$

$$\text{fork}(a.x(a), \text{fork}(b.y(b), z)) = \text{fork}(b.\text{fork}(a.x(a), y(b)), z) \quad (8)$$

$$\text{act}_\sigma(x) = \text{fork}(a.\text{wait}(a, x), \text{act}_\sigma(\text{stop})) \quad (9)$$

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The pomset model

Main theorem

Terms in the algebraic theory of dynamic threads correspond exactly to (isomorphism classes of) “pomsets with holes”.

Put differently:

- ▶ Pomsets with holes form a free model for the algebraic theory of dynamic threads.
- ▶ The equations of the algebraic theory are **sound and complete** w.r.t. equality of pomsets with holes.

The proof uses a normalization-by-evaluation argument.

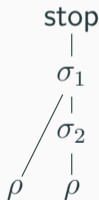
Closed terms denote pomsets

Pomset = partial order labelled by observable actions e.g. σ .
The partial order encodes observable dependencies.

$\text{fork}(a.\text{wait}(a; \text{act}_{\sigma_1}(\text{stop})), \text{act}_{\sigma_2}(\text{stop}))$



$\text{fork}(a.\text{act}_{\rho}(\text{wait}(a; \text{act}_{\sigma_1}(\text{stop}))), \text{act}_{\rho}(\text{act}_{\sigma_2}(\text{stop})))$



What about terms with free variables (i.e. continuations)
and free **tid**'s? Example:

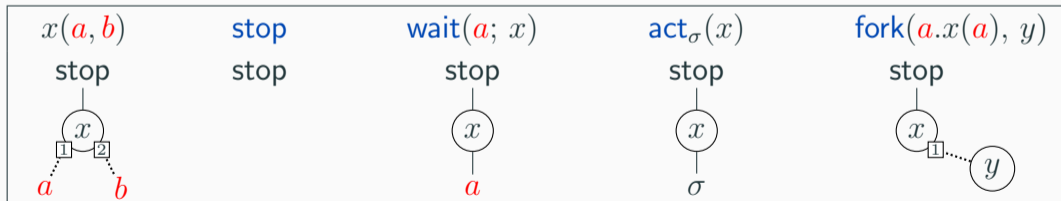
$x : 1 \mid a \vdash \text{fork}(b.\text{wait}(a; x(b)), \text{act}_{\rho}(\text{stop}))$

Pomsets with holes

Pomsets with extra structure:

- ▶ minimal elements representing free thread IDs (in red);
- ▶ elements labelled by variables (the holes);
- ▶ a relation of potential dependencies (dotted lines).

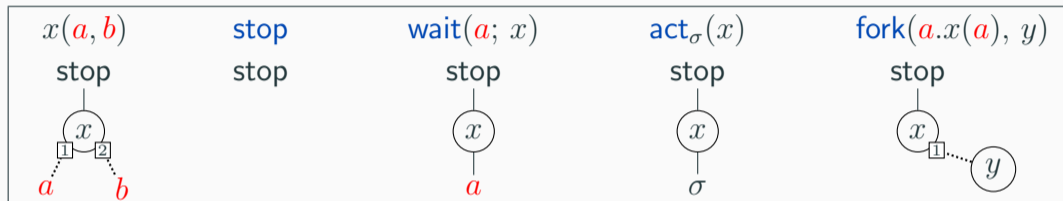
Terms denote pomsets. Algebraic operations act on pomsets.



Define substitution of another pomset for all holes labelled x (monadic bind). The dotted lines become important.

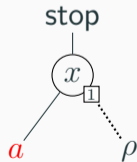
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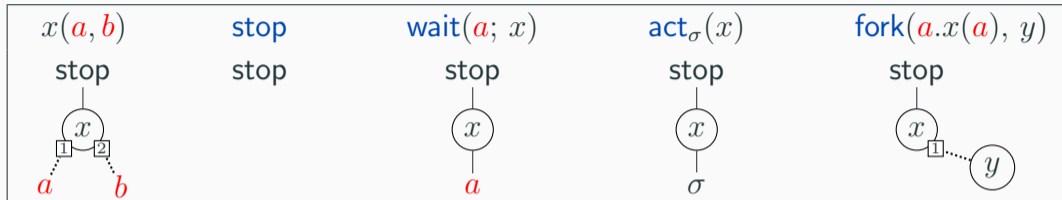


Example denotation:

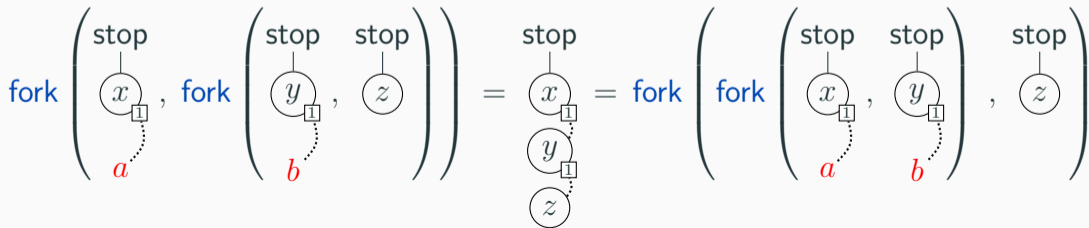
$$x : 1 \mid a \vdash \text{fork}(b.\text{wait}(a; x(b)), \text{act}_{\rho}(\text{stop}))$$



Reasoning graphically about the equations in the algebraic theory



$$\text{fork}(a.x(a), \text{fork}(b.y(b), z)) = \text{fork}(b.\text{fork}(a.x(a), y(b)), z) \quad (8)$$



Further results: adequacy and full abstraction at first order

Framework of algebraic effects: the pomset model of the algebraic theory induces a **monad** on $\text{Set}^{\text{FinRel}}$ via the free algebra construction.

Use the monad to give a **denotational model** to a simply-typed lambda calculus with [fork](#), [wait](#), [stop](#), [act](#) _{σ} .

The denotational semantics matches the operational semantics:

Theorem

Denotational equality implies contextual equivalence.

The converse is true for programs of first-order type.

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More related work

Modelled thread creation (**fork**) and synchronization (**wait**) using a **parameterized** algebraic theory, and the induced monad of pomsets.

Parameterized theories have been used for other effects with binding e.g.:

- ▶ local state
 - ▶ functional logic programming
 - ▶ qubits
 - ▶ urns in probabilistic programming [Staton et al'18]
 - ▶ code pointers [Fiore&Staton'14]
 - ▶ scoped effects [Matache et al'25]
- 

Ongoing work on **handlers** for parameterized effects (Paella) [Sigal et al'HOPE 24].

Advantage of algebraic effects: study the concurrent behaviour independently of the programming language.

Towards a theory of concurrent programming with effects

- ▶ Can we combine with other algebraic effects e.g. state?
- ▶ Can we model other types of concurrency implemented with handlers?
- ▶ Do we need new notions of algebraic theories?
- ▶ Can we get useful equational reasoning principles?

Future work

- ▶ Give more structure to the observable actions, σ .
- ▶ Model more sophisticated concurrency:
 - forking might fail (like in POSIX);
 - communication between parent and child;
 - allowing conflicts between actions (as in event structures).

Example: stop : bool \rightarrow empty wait : tid \rightarrow bool

wait(a , act $_{\sigma_1}$, act $_{\sigma_2}$)

